

## Forklift Starter and Alternator

Forklift Starter and Alternator - A starter motor today is usually a permanent-magnet composition or a series-parallel wound direct current electrical motor together with a starter solenoid mounted on it. Once current from the starting battery is applied to the solenoid, basically through a key-operated switch, the solenoid engages a lever that pushes out the drive pinion which is positioned on the driveshaft and meshes the pinion with the starter ring gear which is found on the flywheel of the engine.

The solenoid closes the high-current contacts for the starter motor, which starts to turn. After the engine starts, the key operated switch is opened and a spring inside the solenoid assembly pulls the pinion gear away from the ring gear. This action causes the starter motor to stop. The starter's pinion is clutched to its driveshaft by an overrunning clutch. This permits the pinion to transmit drive in just a single direction. Drive is transmitted in this particular manner via the pinion to the flywheel ring gear. The pinion remains engaged, for instance since the driver did not release the key as soon as the engine starts or if the solenoid remains engaged as there is a short. This actually causes the pinion to spin independently of its driveshaft.

The actions discussed above will stop the engine from driving the starter. This significant step stops the starter from spinning very fast that it would fly apart. Unless modifications were made, the sprag clutch arrangement will prevent making use of the starter as a generator if it was used in the hybrid scheme mentioned earlier. Usually an average starter motor is intended for intermittent utilization that will prevent it being used as a generator.

The electrical components are made in order to work for more or less 30 seconds in order to stop overheating. Overheating is caused by a slow dissipation of heat is due to ohmic losses. The electrical components are meant to save weight and cost. This is the reason the majority of owner's manuals meant for vehicles recommend the driver to stop for a minimum of ten seconds right after each 10 or 15 seconds of cranking the engine, when trying to start an engine that does not turn over at once.

During the early 1960s, this overrunning-clutch pinion arrangement was phased onto the market. Previous to that time, a Bendix drive was utilized. The Bendix system operates by placing the starter drive pinion on a helically cut driveshaft. As soon as the starter motor begins spinning, the inertia of the drive pinion assembly enables it to ride forward on the helix, hence engaging with the ring gear. Once the engine starts, the backdrive caused from the ring gear allows the pinion to surpass the rotating speed of the starter. At this moment, the drive pinion is forced back down the helical shaft and hence out of mesh with the ring gear.

The development of Bendix drive was made in the 1930's with the overrunning-clutch design called the Bendix Folo-Thru drive, made and introduced in the 1960s. The Folo-Thru drive consists of a latching mechanism along with a set of flyweights in the body of the drive unit. This was better for the reason that the standard Bendix drive used to disengage from the ring once the engine fired, even if it did not stay functioning.

The drive unit is forced forward by inertia on the helical shaft when the starter motor is engaged and begins turning. Afterward the starter motor becomes latched into the engaged position. When the drive unit is spun at a speed higher than what is achieved by the starter motor itself, for instance it is backdriven by the running engine, and then the flyweights pull outward in a radial manner. This releases the latch and enables the overdriven drive unit to become spun out of engagement, thus unwanted starter disengagement can be prevented prior to a successful engine start.